

# Examples of measures with trivial left and non-trivial right random walk tail boundary

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## Abstract

In early 80's Vadim Kaimanovich presented a construction of a non-degenerate measure, on the standard lamplighter group, that has a trivial left and non-trivial right random walk tail boundary. We show that examples of such kind are possible precisely for amenable groups that have non-trivial factors with ICC property.

## 1 Introduction

Let  $G$  be a countable group and  $\nu$  be a probability measure on  $G$ . A measure on  $G$  is called *non-degenerate* if its support generates  $G$  as a semigroup. The  $\nu$ -random walk on  $G$  is defined in the following way. First let  $(X_i)_{i=1}^\infty$  be the i.i.d. process with distribution  $\nu$ . We set  $Z_i = X_1 \cdot \dots \cdot X_i$ . Process  $(Z_i)$  is called the right  $\nu$ -random walk on  $G$ . Similarly, we can define the left random walk by setting  $Z'_i = X_i \cdot \dots \cdot X_1$ . By default, *random walk* will mean right random walk. We will restrict ourselves to non-degenerate measures on groups. If  $\nu$  is a measure on a countable group  $G$ , we may define an opposite measure  $\nu^{-1}$  by  $\nu^{-1}(g) = \nu(g^{-1})$ . It is trivial to see that instead of left random walks, we may consider right random walks with opposite measures. The *tail boundary* or the *tail subalgebra* of random walk  $(Z_i)$  is defined as the intersection  $\bigcap_j \sigma(Z_j, Z_{j+1}, \dots)$ , where  $\sigma(Z_j, Z_{j+1}, \dots)$  denotes the minimal  $\sigma$ -algebra under which all variables  $Z_j, Z_{j+1}, \dots$  are measurable. Pair  $(G, \nu)$  (or, abusing notation, measure  $\nu$  itself) is called Liouville if the tail boundary of  $\nu$ -random walk on  $G$  is trivial. One of the fundamental questions of asymptotic theory of random walks is whether a measure on a group is Liouville. Another notion of boundary is that of the *Poisson boundary*, it is defined as the invariant-set subalgebra of the process  $(Z_i)_{i \in \mathbb{N}}$  under the time-shift action; in the setting of the random walk on group with non-degenerate measure, the Poisson Boundary coincides with the tail boundary (see [KaVe83], [Ka92]), so we will use these notions interchangeably. Due to the Kaimanovich-Vershik entropy

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criterion for boundary triviality [KaVe83], we have that if a measure  $\nu$  on  $G$  has finite Shannon entropy (defined by  $H(\nu) = -\sum_{g \in G} \nu(g) \log \nu(g)$ , assuming  $0 \log 0 = 0$ ), then left and right  $\nu$ -random walks have trivial tail boundaries simultaneously. Surprisingly, this is not the case if the finite entropy assumption is waived: in [Ka83] Kaimanovich constructed an example of a measure on the standard lamplighter group  $\mathbb{Z}/2\mathbb{Z} \wr \mathbb{Z}$  such that the left random walk has trivial tail boundary, while the right random walk has non-trivial. The purpose of the present note is to explore which countable groups admit examples akin to that of Kaimanovich. Our main result is the following:

**Theorem 1.** *Let  $G$  be a countable group. There is a non-degenerate probability measure  $\nu$  on  $G$  with trivial left and non-trivial right random walk tail boundaries iff  $G$  is amenable and has a non-trivial ICC factor-group.*

We remind that a group is called an ICC (short for infinite conjugacy classes) if conjugacy class of each nontrivial element of the group is non-trivial. Note that a finitely-generated group lacks an ICC factor exactly when it is virtually-nilpotent (=has polynomial growth, due to the famous Gromov theorem), see [DuM56], [M56].

We note that using more subtle techniques from [ErKa19], one can prove that the boundary is not only non-trivial, but the action of any ICC factor-group on the corresponding factor-boundary could be made to be essentially free. In this note we only show that the boundary is non-trivial.

It is well known that amenable groups and only them admit non-degenerate Liouville measures, see Theorems 4.2 and 4.3 from [KaVe83]). It is also well known that all measures on groups without ICC factors are Liouville, see [Ja], a self-contained proof could be also found in the second preprint version of [Feta19]. Thus examples of Kaimanovich type are possible only for amenable groups with non-trivial ICC factors. In the sequel we will show that for every such group there is a measure of full support with non-trivial left and trivial right random walk boundary. Our construction is based on that of the breakthrough paper [Feta19] of Frish, Hartman, Tamuz and Vahidi Ferdowsi, where a non-Liouville measure was constructed for every group with an ICC factor, combined with the classic construction of a Liouville measure for every amenable group by Kaimanovich and Vershik [KaVe83] and Rosenblatt [Ro81], although in the proof of non-triviality of boundary we employ the approach similar to that of Ershler and Kaimanovich [ErKa19].

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## 2 A process with heavy tail

Let  $K$  be a random variable such that  $P(K = k) = (1/c)k^{-5/4}$ , for  $k \in \mathbb{N}$ . Consider an i.i.d. process  $(K_i)_{i \in \mathbb{N}}$  (each  $K_i$  has the same distribution as  $K$ ). A number  $i \in \mathbb{N}$  is a record-time if  $K_i \geq K_j$  for all  $j < i$ , and the value  $(K_i)$  is a record-value; we will call pair  $(i, K_i)$  a record, and usually denote it, abusing notation a bit, as  $K_i$ . A record is simple if  $K_i > K_j$  for all  $j < i$ .

The following lemma could be found in [Feta19, Lemma 2.6] and [ErKa19, Sections 2.B and 2.C].

**Lemma 1.** *For almost every realization of the random process  $(K_i)$ , there is  $i_0$  such that*

1. for all  $i \geq i_0$  we have  $\max\{K_1, \dots, K_i\} > i$ ;
2. all record-times starting from  $i_0$  are simple.

We have a random variable  $K$ , let us construct coupled random variable  $Y$ . If  $K = k_0$ , we set  $Y = \text{'red'}$  with probability  $2^{-k_0}$  and  $Y = \text{'blue'}$  with probability  $1 - 2^{-k_0}$ .

Now consider the process  $(K_i, Y_i)_{i=1}^{\infty}$  such that pairs  $(K_i, Y_i)$  form an i.i.d.

Consider a trajectory of the random process  $(K_i, Y_i)_{i \in \mathbb{N}}$ . We will say that this trajectory *stabilizes* if there is  $i_0$  such that

1. for all  $i \geq i_0$  we have  $\max\{K_1, \dots, K_i\} > i$ ;
2. all record-times  $i$  starting from  $i_0$  are simple and  $Y_i = \text{'blue'}$  for these record-times.

We will call the smallest such  $i_0$  (if it exists) the *stabilization time*. Now it is easy to extend the previous lemma in the following way using the Borel-Cantelli lemma:

**Lemma 2.** *Almost every realization of the random process  $(K_i, Y_i)_{i \in \mathbb{N}}$  stabilizes.*

## 3 Construction

Let  $G$  be a group, and  $A$  be a subset of  $G$ . We will say that a finite subset  $F$  of  $G$  is  $(A, \delta)$ -invariant if  $|aF \setminus F| < \delta|F|$  for all  $a \in A$ .

Let  $H$  be a group. Let  $A$  be a finite subset of  $H$ . We will say that an element  $b$  is an  $A$ -lock if for any  $a'_1, a'_2, a''_1, a''_2$  from  $A$ , equality  $a'_1 b a'_2 = a''_1 b a''_2$  implies  $a'_1 = a''_1$  and  $a'_2 = a''_2$ , and sets  $A$  and  $AbA$  are disjoint.

The proof of the following for amenable groups could be found in [Feta19, Proposition 2.5] and in the general case in [ErKa19, Proposition 4.25].

**Lemma 3.** *If  $\Gamma$  is an ICC group, then for every finite subset  $A$  of  $\Gamma$  there is an  $A$ -lock.*

Let  $G$  be a group, and let  $\varphi$  be a canonical epimorphism onto an ICC group  $\Gamma$ . Let  $(c_i)$  be any sequence enumerating all the elements of  $G$ .

We will construct the measure  $\nu$  for the main theorem as a distribution of a certain random variable  $X$  coupled with  $(K, Y)$ .

We will construct the variable in an iterative manner, together with sets  $A_i$ ,  $F_i$ ,  $D_i$  and a sequence  $b_i$  for each  $i \in \mathbb{N}$ .

Let  $A_1 = \{e\}$ . For each  $i \geq 1$  we choose  $F_i$  to be  $((A_i \cup \{c_i\} \cup \{c_i^{-1}\})^{i+1}, 1/i)$ -invariant. We denote  $D_i = F_i^{-1} \cup F_i \cup A_i \cup \{c_i\} \cup \{c_i^{-1}\}$ , for  $i \in \mathbb{N}$ . For each  $i \geq 1$  we choose  $b_i$  to be such that  $\varphi(b_i)$  is a  $\varphi(D_i^{10i+10})$ -lock. For each  $i \in \mathbb{N}$  we set  $A_{i+1} = D_i \cup b_i F_i^{-1} \cup F_i b_i^{-1}$ .

We are ready to construct a random variable  $X$  that is coupled to  $(K, Y)$ . Assume  $K = i$ . If  $Y = \text{“red”}$ , we set  $X = c_i$ . Otherwise let  $X$  be uniformly distributed in  $b_i F_i^{-1}$ .

So let  $\nu$  be the distribution of  $X$ . It is trivial that the support of  $\nu$  is  $G$ . The following proposition appears as a part of Theorem 4.2 from [KaVe83]:

**Proposition 1.** *Let  $\nu$  be a non-degenerate measure on a countable group  $G$ . The Poisson boundary of  $\nu$ -random walk on  $G$  is trivial iff for every  $g \in G$  we have  $\|g * \nu^{*n} - \nu^{*n}\| \rightarrow 0$ .*

**Lemma 4.**  *$\nu^{-1}$ -random walk on  $G$  has trivial Poisson boundary.*

*Proof.* Let  $g$  be fixed. Assuming that  $n$  is big enough, the sequence  $K_1, \dots, K_n$  with probability close to 1 has unique maximal value, and the corresponding  $Y_i = \text{“blue”}$ ; this is a trivial consequence of Lemma 2. So we have that  $(\nu^{-1})^{*n}$  could be decomposed as

$$(\nu^{-1})^{*n} = \sum_{q', q'', m} p_{q', q'', m} \cdot q' * \lambda_{F_m} b_n^{-1} q'' + \eta_n,$$

where  $q', q'' \in A_n^n$ ,  $m > n$ ,  $p_{q', q'', m} \geq 0$ ,  $\lambda_{F_m}$  is the uniform measure on  $F_m$ , and  $\|\eta_n\| \rightarrow 0$  as  $n \rightarrow \infty$ . From this we readily conclude that  $\|(\nu^{-1})^{*n} - g * (\nu^{-1})^{*n}\| \leq 4/n + 4\|\eta_n\|$ , as soon as  $g \in A_n$ , so the assumption of Lemma 1 is fulfilled.  $\square$

Now we will show that the tail boundary is nontrivial. For this we will construct a tail-measurable function and show that its image is nontrivial.

Denote  $W_n = \varphi(A_n^n b_n F_n^{-1} A_n^n)$  for all  $n \in \mathbb{N}$ . Let  $p : \bigcup_n W_n \rightarrow \Gamma$  be a function defined by the formula  $p(q' \varphi(b_n f) q'') = q'$ , where  $q', q'' \in A_n^n$ ,  $f \in \varphi(F_n^{-1})$ . Note that  $p$  is defined properly since by construction  $\varphi(b_n)$  is a  $\varphi(D_i^{10i+10})$ -lock. Note that for any  $w \in W_n$  if  $p(w)$  belongs to  $\bigcup_n W_n$ , then  $p(w) \in W_m$  for some  $m < n$ , since  $p(w) \in A_n^n$  and  $W_m$  is disjoint from  $A_n^n$  for any  $m \geq n$  by the construction of  $b_n$ . For any  $w \in \Gamma$  we define  $t(w)$  as the (possibly empty) set of all  $p(w), p(p(w)), p(p(p(w)))$  that lie in  $\bigcup_i W_i$ . Let  $(K_i, Y_i, X_i)_{i \in \mathbb{N}}$  be the process described above. We can make the following simple observation: if  $i < j$  are bigger than the stabilization time, then  $p(\varphi(Z_i)) \subset p(\varphi(Z_j))$ , This is easy to prove for  $i$  and  $i + 1$  (either  $i + 1$  is a new record-time, and then  $p(\varphi(Z_{i+1})) = \varphi(Z_i)$ , or it is not a new record-time,

and then  $p(\varphi(Z_{i+1})) = p(\varphi(Z_i))$ ; either way we get  $t(\varphi(Z_i)) \subset t(\varphi(Z_{i+1}))$ . Also, if  $i_1$  is at least the second record-time after the stabilization time, then  $\varphi(Z_{i-1}) \in t(\varphi(Z_i))$ . We conclude that for almost every realization of the process  $(K_i, Y_i, X_i)_{i \in \mathbb{N}}$ , the limit  $\lim_{i \rightarrow \infty} t(\varphi(Z_i))$  exists and is equal to  $\bigcup_{i \geq i_0} t(\varphi(Z_i))$ . We define this limit  $\tau(\omega)$ . It is trivial that  $\tau$  is a tail-measurable random variable. Let us collect our observations concerning  $\tau$ .

**Lemma 5.** *1.  $\tau$  is tail-measurable;*

2.  $\tau \subset \bigcup_n W_n$ ;
3.  $\tau \cap W_n$  has at most one element for any  $n \in \mathbb{N}$ ;
4. if  $i_1$  is at least the second record-time after the stabilization time, then  $\varphi(Z_{i-1}) \in \tau(\varphi(Z_i))$ ;
5. if the trajectory of the process stabilizes, then there is  $n_0$ , such that  $\tau \cap \bigcup_{n \geq n_0} W_n$  contains exactly elements of the form  $\varphi(Z_{i-1})$ , where  $i$  runs through all the record-time bigger than the stabilization time, except for the first one.

The purpose of ours is now to prove that the distribution of the random variable  $\tau$  is not concentrated on one point. Denote  $\Omega = (\mathbb{N} \times \{\text{'red'}, \text{'blue'}\} \times G)^{\mathbb{N}}$  the space of trajectories of the random process  $(K_i, Y_i, X_i)_{i \in \mathbb{N}}$ , and

$$\Xi = (\mathbb{N} \times \{\text{'red'}, \text{'blue'}\} \times G)^{\mathbb{N}} \times \mathbb{N},$$

the space of trajectories augmented by values of the stabilization times. Both  $\Omega$  and  $\Xi$  are endowed with probability measures and are naturally isomorphic.

Take any point  $\xi_0$  from the support of the measure on  $\Xi$  and such that the statement of Lemma 2 holds for the corresponding realization of the random process  $(K_i, Y_i, Z_i)$ . For big enough  $m$  there are (at least) two  $\gamma_1, \gamma_2$  such that  $P(\varphi(X) = \gamma_1 | K < m) > 0$  and  $P(\varphi(X) = \gamma_2 | K < m) > 0$ . We fix the realization  $\omega_0$  of the random process that corresponds to  $\xi_0$ . Let  $i_0$  be the stabilization time for that realization. Let  $i_1$  be a record-time that is bigger than the stabilization time and such that the corresponding record-value  $k_{i_1}$  is bigger than  $m$ ; let  $i_2$  be the next record-time. By the previous lemma,  $\varphi(Z_{i_2-1}) \in \tau$ . Consider the neighbourhood of  $\xi_0$  defined by constraints that  $X_i = x_i, K_i = k_i, Y_i = y_i$  for all  $i = 1 \dots i_2 - 1$  and that the stabilization time is not bigger than  $i_1$ . Denote  $S$  the projection of this neighbourhood into  $\Omega$ . Note that  $S$  has positive measure. By construction of  $m$ , there are  $k'_1, y'_1, x'_1$  such that  $\varphi(x'_1) \neq \varphi(x_1), k_1 < m$  and that  $P(K = k'_1, Y = y'_1, X = x'_1) > 0$ . We define a map  $T : A \rightarrow \Omega$  that changes the first triple  $(k_1, y_1, x_1)$  to  $(k'_1, y'_1, x'_1)$ :

$$T(k_1, y_1, x_1, k_2, y_2, x_2, k_3, y_3, x_3, \dots) = (k'_1, y'_1, x'_1, k_2, y_2, x_2, k_3, y_3, x_3, \dots).$$

This map preserves measure up to a positive multiplicative constant, so  $T(S)$  has positive measure. Also, for every  $\omega \in T(S)$  we have that the stabilization time is at most  $i_1$ . We also note that for every  $\omega \in S$ ,  $\tau(\omega) \cap W_{i_1} =$

$\{\varphi(x_1(\omega_0)x_2(\omega_0)\dots x_{i_2-1}(\omega_0))\}$ , and for every  $\omega \in T(S)$ , we have  $\tau(\omega) \cap W_{i_1} = \{\varphi(x'_1x_2(\omega_0)\dots x_{i_2-1}(\omega_0))\}$ , so the distribution of  $\tau$  is not concentrated on one point, since sets of values  $\tau(S)$  and  $\tau(T(S))$  are disjoint.

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